

## Local convergence analysis of two competing two-step iterative methods free of derivatives for solving equations and systems of equations

IOANNIS K. ARGYROS<sup>1,\*</sup> AND SANTHOSH GEORGE<sup>2</sup>

<sup>1</sup> *Department of Mathematical Sciences, Cameron University, Lawton, OK 73505, USA*

<sup>2</sup> *Department of Mathematical and Computational Sciences, National Institute of Technology, Karnataka, Surathkal 575 025, India*

Received April 14, 2018; accepted May 2, 2019

---

**Abstract.** We present the local convergence analysis of two-step iterative methods free of derivatives for solving equations and systems of equations under similar hypotheses based on Lipschitz-type conditions. The methods are in particular useful for solving equations or systems involving non-differentiable terms. A comparison is also provided using suitable numerical examples.

**AMS subject classifications:** 47H09, 47H10, 65G99, 65H10, 49M15

**Key words:** two-step secant method, two-step Kurchatov method, local convergence, divided differences, Fréchet-derivative, radius of convergence, Lipschitz conditions

---

### 1. Introduction

Numerous problems in mathematics, computational sciences, engineering and related sciences using mathematical modeling [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 14, 11, 12, 13, 16, 15, 17] can be reduced to locating a solution  $x^*$  of the nonlinear equation in the form

$$F(x) = 0,$$

where  $X, Y$  are Banach spaces,  $D$  is nonempty, open, convex, and  $F : D \subseteq X \rightarrow Y$  is Fréchet-differentiable.

Analytic solutions or closed form solutions are hard or impossible to find in general. That explains why researchers utilize iterative methods to generate a sequence approximating  $x^*$ .

In this study, we present the local convergence of two-step secant method (TSSM) and the two-step Kurchatov-type method (TSKM) defined, respectively, for each  $n = 0, 1, 2, \dots$  by

$$x_{n+1} = x_n - [x_n, y_n; F]^{-1}F(x_n) \tag{1}$$

$$y_{n+1} = x_{n+1} - [x_{n+1}, y_n; F]^{-1}F(x_{n+1})$$

$$x_{n+1} = x_n - [2y_n - x_n, y_n; F]^{-1}F(x_n) \tag{2}$$

$$y_{n+1} = x_{n+1} - [2y_n - x_n, x_n; F]F(x_{n+1}),$$

---

\*Corresponding author. *Email addresses:* `iargyros@cameron.edu` (I. K. Argyros), `sgeorge@nitk.edu.in` (S. George)

where  $x_0, y_0 \in D$  are initial points and  $[\cdot, \cdot; F] : D \times D \rightarrow \mathcal{L}(X, Y)$  is a divided difference of order one [16, 15] for  $F$  on  $D$  satisfying

$$[x, y; F](x - y) = F(x) - F(y) \text{ for each } x, y \text{ with } x \neq y,$$

and  $F'(x) = [x, x; F]$ , if  $F$  is Fréchet-differentiable. TSSM uses two inverses and three function evaluations per complete step, whereas TSKM uses one inverse and four function evaluations.

The rest of the paper is structured as follows: Section 2 and Section 3 contain the local convergence of TSSM and TSKM, respectively, under similar Lipschitz-type hypotheses. The numerical examples in Section 4 conclude this paper.

## 2. Local convergence I

We present the local convergence analysis of TSSM based on scalar parameters and functions. Let  $\alpha \geq 0, \beta \geq 0$  and  $b > 0$  with  $\alpha + \beta \neq 0$ . Define parameters  $\rho_0, \rho_1$  and functions  $f$  and  $h_f$  on the interval  $[0, \rho_0]$  by

$$\rho_0 = \frac{1}{\alpha + \beta}, \quad \rho_1 = \frac{1}{\alpha + \beta + b},$$

$$f(t) = \left(b + \frac{\alpha b t}{1 - (\alpha + b)t} + \beta\right)t$$

and

$$h_f(t) = f(t) - 1.$$

We have that  $h_f(0) = -1$  and  $h_f(t) \rightarrow +\infty$  as  $t \rightarrow \rho_0^-$ . The intermediate value theorem assures that equation  $h_f(t) = 0$  has solutions on the interval  $(0, \rho_0)$ . Denote by  $\rho^*$  the smallest such solution. Notice that  $h_f(\rho_1) = 0$ , so  $\rho^* \leq \rho_1$ . Then, we have that for each  $t \in [0, \rho^*)$

$$0 \leq \frac{bt}{1 - (\alpha + \beta)t} < 1$$

and

$$0 \leq f(t) < 1.$$

Let  $U(z, \lambda)$  and  $\bar{U}(z, \lambda)$  denote the open and closed balls in  $X$ , respectively, where  $z \in X$  is the center and  $\lambda > 0$  is the radius. The local convergence analysis of TSSM is also based on the hypotheses (H):

( $h_1$ )  $F : D \subset X \rightarrow Y$  is a continuously Fréchet differentiable operator and  $[\cdot, \cdot; F] : D \times D \rightarrow \mathcal{L}(X, Y)$  is a divided difference of order one.

( $h_2$ ) There exist parameters  $\alpha \geq 0, \beta \geq 0$  with  $\alpha + \beta \neq 0, x^* \in D$  such that

$$F(x^*) = 0, \quad F'(x^*)^{-1} \in L(Y, X)$$

and for each  $x, y \in D$

$$\|F'(x^*)^{-1}([x, y; F] - F'(x^*))\| \leq \alpha \|x - x^*\| + \beta \|y - x^*\|.$$

Set  $D_0 = D \cap U(x^*, \rho_0)$ , where  $\rho_0$  was defined previously.

(h<sub>3</sub>) There exists  $b > 0$  such that for each  $x, y \in D_0$

$$\|F'(x^*)^{-1}([x, y; F] - [x, x^*; F])\| \leq b\|y - x^*\|.$$

(h<sub>4</sub>)  $\bar{U}(x^*, \rho^*) \subset D$ , where  $\rho^*$  was defined previously.

(h<sub>5</sub>) There exists  $R^* \geq \rho^*$  such that

$$R^* < \frac{1}{\beta}, \beta \neq 0.$$

Set  $D_1 = D \cap \bar{U}(x^*, R^*)$ .

**Theorem 1.** *Suppose that the hypotheses (H) hold. Then, sequences  $\{x_n\}, \{y_n\}$  starting from  $x_0, y_0 \in U(x^*, \rho^*) - \{x^*\}$  and generated by TSSM are well defined in  $U(x^*, \rho^*)$  for each  $n = 0, 1, 2, \dots$ , remain in  $U(x^*, \rho^*)$  and converge to  $x^*$ . Moreover, the following estimates hold for each  $n = 0, 1, 2, \dots$*

$$\|x_{n+1} - x^*\| \leq \frac{b\|y_n - x^*\|}{1 - (\alpha\|x_n - x^*\| + \beta\|y_n - x^*\|)}\|x_n - x^*\| \leq \|x_n - x^*\| < \rho^* \quad (3)$$

and

$$\|y_{n+1} - x^*\| \leq \frac{b\|y_n - x^*\|}{1 - (\alpha\|x_{n+1} - x^*\| + \beta\|y_n - x^*\|)}\|x_{n+1} - x^*\|. \quad (4)$$

Furthermore, the limit point  $x^*$  is the only solution to equation  $F(x) = 0$  in  $D_1$ , where  $D_1$  is defined in (h<sub>5</sub>).

**Proof.** Let  $x, y \in U(x^*, \rho^*)$ . Using (h<sub>2</sub>), we have in turn that

$$\begin{aligned} \|F'(x^*)^{-1}([x, y; F] - F'(x^*))\| &\leq \alpha\|x - x^*\| + \beta\|y - x^*\| \\ &< (\alpha + \beta)\rho^* < 1. \end{aligned} \quad (5)$$

In view of (5) and the Banach lemma on invertible operators [5, 6, 7, 13],  $[x, y; F]^{-1} \in L(Y, X)$  and

$$\|[x, y; F]^{-1}F'(x^*)\| \leq \frac{1}{1 - (\alpha\|x - x^*\| + \beta\|y - x^*\|)}. \quad (6)$$

In particular,  $[x_0, y_0; F]^{-1} \in L(Y, X)$ , since  $x_0, y_0 \in U(x^*, \rho^*)$ . By the first substep of TSSM, we can write

$$\begin{aligned} x_1 - x^* &= x_0 - x^* - [x_0, y_0; F]^{-1}F(x_0) \\ &= [x_0, y_0; F]^{-1}([x_0, y_0; F] - [x_0, x^*; F])(x_0 - x^*). \end{aligned} \quad (7)$$

By (h<sub>3</sub>), (6) for  $x = x_0, y = y_0$  and (7), we get in turn

$$\begin{aligned} \|x_1 - x^*\| &\leq \|[x_0, y_0; F]^{-1}F'(x^*)\| \|F'(x^*)^{-1}([x_0, y_0; F] - [x_0, x^*; F])(x_0 - x^*)\| \\ &\leq \frac{b\|y_0 - x^*\|}{1 - (\alpha\|x_0 - x^*\| + \beta\|y_0 - x^*\|)}\|x_0 - x^*\| \\ &\leq \|x_0 - x^*\| < \rho^*, \end{aligned}$$

so (3) holds for  $n = 0$  and  $x_1 \in U(x^*, \rho^*)$  and  $[x_1, y_0; F]^{-1} \in L(Y, X)$ . We also have by (6) that

$$\|[x_1, y_0; F]^{-1}F'(x^*)\| \leq \frac{1}{1 - (\alpha\|x_1 - x^*\| + \beta\|y_0 - x^*\|)}.$$

Moreover, by the second substep of TSSM, we can write that

$$\begin{aligned} y_1 - x^* &= x_1 - x^* - [x_1, y_0; F]^{-1}F(x_1) \\ &= [x_1, y_0; F]^{-1}([x_1, y_0; F] - [x_1, x^*; F])(x_1 - x^*), \end{aligned}$$

so

$$\begin{aligned} \|y_1 - x^*\| &\leq \frac{b\|y_0 - x^*\|\|x_1 - x^*\|}{1 - (\alpha\|x_1 - x^*\| + \beta\|y_0 - x^*\|)} \\ &\leq \frac{b\rho^*}{1 - (\alpha + \beta)\rho^*}\|x_1 - x^*\| < \rho^*, \end{aligned}$$

which shows (4) for  $n = 0$  and  $y_1 \in U(x^*, \rho^*)$ . The induction for (3) and (4) is completed analogously if  $x_0, y_0, x_1, y_1$  are replaced by  $x_m, y_m, x_{m+1}, y_{m+1}$  in the preceding estimates, respectively. Then, from the estimates

$$\|x_{m+1} - x^*\| \leq \mu_1\|x_m - x^*\| < \rho^*$$

and

$$\|y_{m+1} - x^*\| \leq \mu_2\|x_{m+1} - x^*\| < \rho^*,$$

where  $\mu_1 = \frac{b\rho^*}{1 - (\alpha + \beta)\rho^*} \in [0, 1)$  and  $\mu_2 = f(\rho^*) \in [0, 1)$ , we deduce that  $\lim_{m \rightarrow +\infty} x_m = \lim_{m \rightarrow +\infty} y_m = x^*$ ,  $x_{m+1} \in U(x^*, \rho^*)$  and  $y_{m+1} \in U(x^*, \rho^*)$ . The uniqueness part is shown by letting  $T = [x^*, y^*; F]$  for some  $y^* \in D_1$  with  $F(y^*) = 0$ . Using  $(h_2)$  and  $(h_5)$ , we obtain in turn that

$$\|F'(x^{-1}([x^*, y^*; F] - F'(x^*)))\| \leq \beta\|y^* - x^*\| \leq \beta R < 1,$$

so  $T^{-1} \in L(Y, X)$ . Finally, from the identity

$$0 = F(x^*) - F(y^*) = [x^*, y^*; F](x^* - y^*),$$

we conclude that  $x^* = y^*$ . □

### 3. Local convergence II

In this section, the local convergence of TSKM is presented in the way analogous to that shown in Section 2 for TSSM. Let  $a \geq 0, b_1 \geq 0, p \geq 0, q \geq 0, a + b_1 \neq 0$  and  $c > 0$  be given parameters. Define parameters  $r_0, r_1$ , functions  $g_1$  and  $h_{g_1}$  on interval  $[0, r_0)$  by

$$\begin{aligned} r_0 &= \frac{2}{a + \sqrt{a^2 + 16c}}, \quad r_1 = \frac{2}{a + b_1 + \sqrt{(a + b_1)^2 + 32c}} \\ g_1(t) &= \frac{b_1 + 4ct}{1 - (a + 4ct)t}t \end{aligned}$$

and

$$h_{g_1}(t) = g_1(t) - 1.$$

Notice that  $h_{g_1}(r_1) = 0$  and  $r_1$  is the only solution to equation  $h_{g_1}(t) = 0$  in  $(0, r_0)$ . Moreover, define functions  $g_2$  and  $h_{g_2}$  of the interval  $[0, r_0)$  by

$$g_2(t) = \frac{p\left[\frac{(b_1+4ct)t}{1-(a+4ct)t} + 1\right] + q + 4ct}{1 - (a + 4ct)t}t$$

and

$$h_{g_2}(t) = g_2(t) - 1.$$

We get  $h_{g_2}(0) = -1 < 0$  and  $h_{g_2}(t) \rightarrow +\infty$  as  $t \rightarrow r_0^-$ . Denote by  $r_2$  the smallest solution to equation  $h_{g_2}(t) = 0$  in  $(0, r_1)$ .

Define the radius of convergence  $r^*$  by

$$r^* = \min\{r_1, r_2\}. \tag{8}$$

Then, we have that for each  $t \in [0, r^*)$ ,

$$0 \leq g_i(t) < 1, \quad i = 1, 2.$$

The local convergence analysis of TSKM is based on hypotheses (A):

1.  $(a_1) = (h_1)$

$(a_2)$  There exist  $a \geq 0, c \geq 0, x^* \in D$  such that  $F(x^*) = 0, F'(x^*)^{-1} \in L(Y, X)$  for each  $x, y \in D$

$$\|F'(x^*)^{-1}(F'(x) - F'(x^*))\| \leq a\|x - x^*\|$$

and

$$\|F'(x^*)^{-1}([2y - x, x; F] - F'(y))\| \leq c\|y - x\|^2$$

Set  $D_2 = D \cap \bar{U}(x^*, r_0)$ , where  $r_0$  was defined previously.

$(a_3)$  There exists  $b \geq 0, p \geq 0, q \geq 0$  such that for each  $x, y \in D_2$

$$\|F'(x^*)^{-1}([x, y; F] - [x, x^*; F])\| \leq b\|y - x^*\|$$

and

$$\|F'(x^*)^{-1}([x, x^*; F] - F'(y))\| \leq p\|x - y\| + q\|y - x^*\|.$$

$(a_4)$   $\bar{U}(x^*, 3r^*) \subseteq D$ , where  $r^*$  was defined previously.

$(a_5)$  There exists  $R_1^* \geq R^*$  such that

$$R_1^* < \frac{2}{a}, a \neq 0.$$

Set  $D_3 = D \cap \bar{U}(x^*, R_1^*)$ .

**Theorem 2.** *Suppose that the hypotheses (A) hold. Then, sequences  $\{x_n\}, \{y_n\}$  starting from  $x_0, y_0 \in U(x^*, r^*) - \{x^*\}$  and generated by TSKM are well defined in  $U(x^*, r^*)$  for each  $n = 0, 1, 2, \dots$ , remain in  $U(x^*, r^*)$ , and converges to  $x^*$ . Moreover, the following estimates hold for each  $n = 0, 1, 2, \dots$*

$$\|x_{n+1} - x^*\| \leq \frac{b\|y_n - x^*\| + c\|y_n - x_n\|^2}{1 - (a\|x_n - x^*\| + c\|y_n - x_n\|^2)} \|x_n - x^*\| \leq \|x_n - x^*\| < r^* \quad (9)$$

and

$$\|y_{n+1} - x^*\| \leq \frac{p\|x_{n+1} - y_n\| + q\|y_n - x^*\| + c\|y_n - x_n\|^2}{1 - (a\|x_n - x^*\| + c\|y_n - x_n\|^2)} \|x_{n+1} - x^*\|. \quad (10)$$

Furthermore, the limit point  $x^*$  is the only solution to equation  $F(x) = 0$  in  $D_3$ .

**Proof.** Let  $x, y \in U(x^*, r^*)$  and set  $Q = [2y - x, x; F]$ . Using  $(a_2)$  and (8), we have in turn that

$$\begin{aligned} & \|F'(x^*)^{-1}(F'(x^*) - Q)\| \\ &= \|F'(x^*)^{-1}(F'(x^*) - F'(y)) + (F'(y) - [2y - x, x; F])\| \\ &\leq \|F'(x^*)^{-1}(F'(y) - F'(x^*))\| + \|F'(x^*)^{-1}([2y - x, x; F] - F'(y))\| \\ &\leq a\|y - x^*\| + c\|y - x\|^2 \\ &\leq ar^* + c(\|y - x^*\| + \|x^* - x\|)^2 \\ &\leq ar^* + 4c(r^*)^2 < 1, \end{aligned}$$

so  $Q^{-1} \in L(Y, X)$ ,

$$\|Q^{-1}F'(x^*)\| \leq \frac{1}{1 - (a\|y - x^*\| + c\|x - y\|^2)} \quad (11)$$

and  $[2y_0 - x_0, x_0; F]^{-1} \in L(Y, X)$  for  $x = x_0$  and  $y = y_0$ . Hence,  $x_1$  and  $y_1$  are well defined by the first and the second substep of TSKM. Notice that condition  $(a_4)$  guarantees that for  $x, y \in U(x^*, r^*)$  we have  $2y - x \in U(x^*, r^*) \subseteq D$ . By  $(a_2)$  and  $(a_3)$ , we get in turn the estimate

$$\begin{aligned} & \|F'(x^*)^{-1}(Q - [x_0, x^*; F])\| \\ &\leq \|F'(x^*)^{-1}([y_0, x^*; F] - F'(y_0)) + (F'(y_0) - [2y_0 - x_0, x_0; F])\| \\ &\leq \|F'(x^*)^{-1}([y_0, x^*; F] - F, (y_0))\| + \|F'(x^*)^{-1}(F'(y_0) - [2y_0 - x_0, x_0; F])\| \\ &\leq b\|y_0 - x^*\| + c\|y_0 - x_0\|^2. \end{aligned} \quad (12)$$

In view of the first substep of TSKM, (8), (11) and (12), we obtain in turn from

$$\begin{aligned} x_1 - x_0 &= x_0 - x^* - Q^{-1}F(x_0) \\ &= Q^{-1}(Q - [x_0, x^*; F])(x_0 - x^*), \end{aligned}$$

so

$$\begin{aligned} \|x_1 - x_0\| &\leq \mu_3 \|x_0 - x^*\| \\ &\leq \|x_0 - x^*\| < r^*, \end{aligned}$$

where  $\mu_3 = \frac{b\|y_0-x^*\|+c\|x_0-y_0\|^2}{1-(a\|y_0-x^*\|+c\|x_0-y_0\|^2)} \in [0, 1)$ , which shows (9) for  $n = 0$  and  $x_1 \in U(x^*, r^*)$ . Similarly, from the second substep of TSKM, we can also write

$$\begin{aligned} y_1 - x^* &= x_1 - x^* - Q^{-1}F(x_1) \\ &= Q^{-1}((2y_0 - x_0, x_0; F] - F'(y_0)) + (F'(y_0) - [x_1, x^*; F])(x_1 - x^*), \end{aligned}$$

so

$$\begin{aligned} &\|y_1 - x^*\| \\ &\leq \frac{\|F'(x^*)^{-1}([2y_0 - x_0, x_0; F] - F'(y_0))\| + \|F'(x^*)^{-1}(F'(y_0) - [x_1, x^*; F])\|}{1 - (a\|x_0 - x^*\| + c\|y_0 - x_0\|^2)} \\ &\quad \times \|x_1 - x^*\| \\ &\leq \frac{p\|x_1 - y_0\| + q\|y_0 - x^*\| + c\|y_0 - x_0\|^2}{1 - (a\|x_0 - x^*\| + c\|y_0 - x_0\|^2)} \|x_1 - x^*\| \\ &\leq g_2(\|x_0 - x^*\|) \|x_1 - x^*\| \leq \|x_1 - x^*\| < r^*, \end{aligned}$$

which shows (10) for  $n = 0$  and  $y_1 \in U(x^*, r^*)$ . Then, from the estimates

$$\|x_{m+1} - x^*\| \leq \mu_3 \|x_n - x^*\| < r^*,$$

and

$$\|y_{n+1} - x^*\| \leq \mu_4 \|x_{m+1} - x^*\| < r^*,$$

where  $\mu_4 = g_2(\|x_0 - x^*\|) \in [0, 1)$ , we obtain  $\lim_{m \rightarrow +\infty} x_m = \lim_{m \rightarrow +\infty} y_m = x^*$  and  $x_{m+1}, y_{m+1} \in U(x^*, r^*)$ . As in Theorem 1, but using (a<sub>2</sub>) and (a<sub>5</sub>) for  $P = \int_0^1 F'(x^* + \theta(y^* - x^*))d\theta$ , we obtain

$$\begin{aligned} \|F'(x^*)^{-1}(P - F'(x^*))\| &\leq \int_0^1 \theta \|y^* - x^*\| d\theta \\ &\leq \frac{a}{2} \|y^* - x^*\| \leq \frac{a}{2} R_1^* < 1, \end{aligned}$$

so  $P^{-1} \in L(Y, X)$ . Then, from the identity

$$0 = F(y^*) - F(x^*) = P(y^* - x^*),$$

we derive that  $x^* = y^*$ . □

**Remark 1.** Condition (a<sub>4</sub>) can be weakened if replaced by (a<sub>4</sub>)'  $\bar{U}(x^*, r^*) \subseteq D$  and for each  $x, y \in D$

$$2y - x \in D. \tag{13}$$

Condition (13) certainly holds if  $D = X$  (see also [1, 2, 3, 4, 5, 6, 7]).

#### 4. Numerical examples

Let  $X = Y = \mathbb{R}^k$ ,  $k$  be a positive integer equipped with the standard difference [13], and for

$$\begin{aligned}x_m &= (x_m^{(1)}, x_m^{(2)}, \dots, x_m^{(k)}) \\y_m &= (y_m^{(1)}, y_m^{(2)}, \dots, y_m^{(k)}),\end{aligned}$$

there exists  $i = 1, 2, \dots, k$  such that  $x_m^{(i)} = y_m^{(i)}$ . Then, we cannot use TSSM or TSKM in the form (1) and (2). Assuming that  $x_0^{(i)} \neq y_0^{(i)}$ ,  $y_0^{(i)} \neq x_1^{(i)}$  for each  $i = 1, 2, \dots, k$ ,  $[x_0, y_0; F]^{-1}$  and  $[x_1, y_0; F]^{-1} \in L(Y, X)$ , we can use a method similar to the TSSM method defined for each  $n = 0, 1, 2, \dots$ , by

$$\begin{aligned}x_{n+1} &= x_n - [v_j, w_j; F]^{-1}F(x_n) \\y_{n+1} &= x_{n+1} - [z_{j+1}, w_j; F]^{-1}F(x_{n+1}),\end{aligned}\tag{14}$$

where  $j = 0, 1, 2, \dots, n$  is the smallest index for which  $v_j^{(i)} \neq w_j^{(i)}$  and  $z_{j+1}^{(i)} \neq w_j^{(i)}$ . Then, method (14) is always well defined and can be used to solve equations containing non-differentiable terms. Similarly, assume that  $[2y_0 - x_0, x_0; F]^{-1}$  and  $[2x_1 - y_0, y_0; F]^{-1} \in L(Y, X)$ ,  $x_0^{(i)} \neq y_0^{(i)}$  and  $y_0^{(i)} \neq x_1^{(i)}$  for each  $i = 1, 2, \dots, k$ . Then, the method corresponding to TSKM is defined by

$$\begin{aligned}x_{n+1} &= x_n - [2w_j - v_j, v_j; F]^{-1}F(x_n) \\y_{n+1} &= x_{n+1} - [2w_j - v_j, v_j; F]^{-1}F(x_{n+1}).\end{aligned}\tag{15}$$

Clearly, methods (14) and (15) generalize methods (1) and (2) since they coincide with those for  $j = n$ , respectively.

Next, we shall show the convergence of method (14) under similar conditions. Let us consider hypotheses (H'):

1.  $(h'_1) = (h_1)$

2.  $(h'_2) = (h_2)$

$(h'_3)$  There exists  $\gamma \geq 0, \delta \geq 0$  such that for each  $x, y, z \in D_0$

$$\|F'(x^*)^{-1}([x, y; F] - [z, x^*; F])\| \leq \gamma\|x - z\| + \delta\|y - x^*\|.$$

$(h'_4)$   $\bar{U}(x^*, \bar{\rho}^*) \subset D$ , where  $\bar{\rho}^* = \frac{1}{\alpha + \beta + 2\gamma + \delta}$ .

$(h'_5)$  There exists  $\bar{R}^* \geq \bar{\rho}^*$  such that

$$\bar{R}^* < \frac{1}{\beta}, \beta \neq 0.$$

Let  $D_5 = D \cap \bar{U}(x^*, \bar{R}^*)$ .



**Theorem 3.** *Suppose that the hypotheses (H') hold. Then, sequences  $\{x_n\}, \{y_n\}$  starting from  $x_0, y_0 \in U(x^*, \bar{\rho}^*) - \{x^*\}$  and generated by method (14) are well defined in  $U(x^*, \bar{\rho}^*)$ , remain in  $U(x^*, \bar{\rho}^*)$  for each  $n = 0, 1, 2, \dots$ , and converge to  $x^*$ . Moreover, the following estimates hold:*

$$\begin{aligned} \|x_{n+1} - x^*\| &\leq \frac{\gamma\|v_j - x_n\| + \delta\|w_j - x^*\|}{1 - (\alpha\|v_j - x^*\| + \beta\|w_j - x^*\|)} \|x_n - x^*\| \\ &\leq \frac{\gamma(\|v_j - x^*\| + \|x_n - x^*\|) + \delta\|w_j - x^*\|}{1 - (\alpha\|v_j - x^*\| + \beta\|w_j - x^*\|)} \|x_n - x^*\| \\ &\leq \frac{(2\gamma + \delta)\bar{\rho}^*}{1 - (\alpha + \beta)\bar{\rho}^*} \|x_n - x^*\| \leq \|x_n - x^*\| < \bar{\rho}^* \end{aligned} \tag{16}$$

and

$$\begin{aligned} \|y_{n+1} - x^*\| &\leq \frac{\gamma\|z_{j+1} - x_{n+1}\| + \delta\|w_j - x^*\|}{1 - (\alpha\|z_{j+1} - x^*\| + \beta\|w_j - x^*\|)} \|x_{n+1} - x^*\| \\ &\leq \frac{\gamma(\|z_{j+1} - x^*\| + \|x_{n+1} - x^*\|) + \delta\|w_j - x^*\|}{1 - (\alpha\|z_{j+1} - x^*\| + \beta\|w_j - x^*\|)} \|x_{n+1} - x^*\| \\ &\leq \frac{(2\gamma + \delta)\bar{\rho}^*}{1 - (\alpha + \beta)\bar{\rho}^*} \|x_{n+1} - x^*\| \leq \|x_{n+1} - x^*\| < \bar{\rho}^*. \end{aligned} \tag{17}$$

Furthermore, the limit point  $x^*$  is the only solution to equation  $F(x) = 0$  in  $D_5$ .

**Proof.** Use the proof of Theorem 1, the identities

$$\begin{aligned} x_{n+1} - x^* &= ([v_j, w_j; F]^{-1}F'(x^*)) \\ &\quad \times (F'(x^*)^{-1}([v_j, w_j; F] - [x_n, x^*; F]))(x_n - x^*) \end{aligned}$$

and

$$\begin{aligned} y_{n+1} - x^* &= ([z_{j+1}, v_j; F]^{-1}F'(x^*)) \\ &\quad \times (F'(x^*)^{-1}([z_{j+1}, w_j; F] - [x_{n+1}, x^*; F]))(x_{n+1} - x^*) \end{aligned}$$

to arrive at estimates (16) and (17), respectively. □

The hypotheses (A') are:

1.  $(a'_1) = (a_1)$
2.  $(a'_2) = (h_2)$
3.  $(a'_3) = (h_3)$

$(a'_4)$   $\bar{U}(x^*, \bar{r}^*) \subset D$ , where  $\bar{r}^* = \frac{1}{3\alpha + \beta + 4\gamma + \delta}$ .

$(a'_5)$  There exists  $\bar{R}_1^* \geq \bar{r}^*$  such that

$$\bar{R}_1^* < \frac{1}{\beta}, \beta \neq 0.$$

Let  $D_6 = D \cap \bar{U}(x^*, \bar{R}_1^*)$ .

**Theorem 4.** *Suppose that the hypotheses (A') hold. Then, sequences  $\{x_n\}, \{y_n\}$  starting from  $x_0, y_0 \in U(x^*, \bar{r}^*) - \{x^*\}$  and generated by method (15) are well defined in  $U(x^*, \bar{r}^*)$ , remain in  $U(x^*, \bar{r}^*)$  for each  $n = 0, 1, 2, \dots$ , and converge to  $x^*$ . Moreover, the following estimates hold:*

$$\begin{aligned} \|x_{n+1} - x^*\| &\leq \frac{\gamma\|2w_j - v_j - x_n\| + \delta\|v_j - x^*\|}{1 - (\alpha\|2w_j - v_j - x^*\| + \beta\|v_j - x^*\|)} \|x_n - x^*\| \\ &\leq \frac{\gamma(2\|w_j - x^*\| + \|v_j - x^*\| + \|x_n - x^*\|) + \delta\|v_j - x^*\|}{1 - (\alpha(2\|w_j - x^*\| + \|v_j - x^*\|) + \beta\|v_j - x^*\|)} \|x_n - x^*\| \\ &\leq \frac{(4\gamma + \delta)\bar{r}^*}{1 - (3\alpha + \beta)\bar{r}^*} \|x_n - x^*\| \leq \|x_n - x^*\| < \bar{r}^*, \end{aligned} \tag{18}$$

and

$$\begin{aligned} \|y_{n+1} - x^*\| &\leq \frac{\gamma\|2w_j - v_j - x_{n+1}\| + \delta\|v_j - x^*\|}{1 - (\alpha\|2w_j - v_j - x^*\| + \beta\|v_j - x^*\|)} \|x_{n+1} - x^*\| \\ &\leq \frac{\gamma(2\|w_j - x^*\| + \|v_j - x^*\| + \|x_{n+1} - x^*\|) + \delta\|v_j - x^*\|}{1 - (\alpha(2\|w_j - x^*\| + \|v_j - x^*\|) + \beta\|v_j - x^*\|)} \|x_{n+1} - x^*\| \\ &\leq \frac{(4\gamma + \delta)\bar{r}^*}{1 - (3\alpha + \beta)\bar{r}^*} \|x_{n+1} - x^*\| \leq \|x_{n+1} - x^*\| < \bar{r}^*. \end{aligned} \tag{19}$$

Furthermore, the limit point  $x^*$  is the only solution to equation  $F(x) = 0$  in  $D_6$ .

**Proof.** Use the proof of Theorem 2, the identities

$$\begin{aligned} x_{n+1} - x^* &= ([2w_j - v_j, w_j; F]^{-1}F'(x^*)) \\ &\quad \times (F'(x^*)^{-1}([2w_j - v_j, v_j; F] - [x_n, x^*; F]))(x_n - x^*) \end{aligned}$$

and

$$\begin{aligned} y_{n+1} - x^* &= ([2w_j - v_j, v_j; F]^{-1}F'(x^*)) \\ &\quad \times (F'(x^*)^{-1}([2w_j - v_j, v_j; F] - [x_{n+1}, x^*; F]))(x_{n+1} - x^*) \end{aligned}$$

to arrive at estimates (18) and (19), respectively. □

**Example 1.** *Let us consider the system for  $h = (h_1, h_2)^T$*

$$\begin{aligned} f_1(h) &= 3h_1^2h_2 + h_2^2 - 1 + |h_1 - 1| = 0 \\ f_2(h) &= h_1^4 + h_1h_2^3 - 1 + |h_2| = 0 \end{aligned}$$

which can be written as  $F(h) = 0$ , where  $F = (f_1, f_2)^T$ . Using the divided difference,  $([a, b; F]_{ij})_{i,j=1}^2 \in L(\mathbb{R}^2, \mathbb{R}^2)$  [13], for  $x_{-1} = (1, 0)^T, x_0 = (5, 5)^T$ , we obtain by (2) Hence, the solution  $p$  is given by  $p = (0.894655373334687, 0.3278626421746298)^T$ . Notice that mapping  $F$  is not differentiable, so the earlier results mentioned in the introduction of this study cannot be used.

$n$	$x_n^{(1)}$	$x_n^{(2)}$	$\ x_n - x_{n-1}\ $
0	5	5	5
1	1	0	5
2	0.909090909090909	0.363636363636364	3.0636E-01
3	0.894886945874111	0.329098638203090	3.453E-02
4	0.894655531991499	0.327827544745569	1.271E-03
5	0.894655373334793	0.327826521746906	1.022E-06
6	0.8946655373334687	0.327826521746298	6.089E-13
7	0.8946655373334687	0.327826421746298	2.710E-20

Table 1:

**Example 2.** We consider the boundary problem appearing in many studies of applied sciences [6] given by

$$\begin{aligned} \varphi'' + \varphi^{1+\lambda} + \varphi^2 &= 0, \quad \lambda \in [0, 1] \\ \varphi(0) &= \varphi(1) = 0. \end{aligned} \tag{20}$$

Let  $h = \frac{1}{l}$ , where  $l$  is a positive integer and set  $s_i = ih, i = 1, 2, \dots, l - 1$ . The boundary conditions are then given by  $\varphi_0 = \varphi_n = 0$ . We shall replace the second derivative  $\varphi''$  by the popular divided difference

$$\begin{aligned} \varphi''(t) &\approx \frac{[\varphi(t+h) - 2\varphi(t) + \varphi(t-h)]}{h^2} \\ \varphi''(s_i) &= \frac{\varphi_{i+1} - 2\varphi_i + \varphi_{i-1}}{h^2}, \quad i = 1, 2, \dots, l - 1. \end{aligned} \tag{21}$$

Using (20) and (21), we obtain the system of equations defined by

$$\begin{aligned} 2\varphi_1 - h^2\varphi_1^{1+\lambda} - h^2\varphi_1^2 - \varphi_2 &= 0 \\ -\varphi_{i-1} + 2\varphi_i - h^2\varphi_i^{1+\lambda} - h^2\varphi_i^2 - \varphi_{i+1} &= 0 \\ -\varphi_{l-2} + 2\varphi_{l-1} - h^2\varphi_{l-1}^{1+\lambda} - h^2\varphi_{l-1}^2 &= 0. \end{aligned}$$

Define operator  $F : \mathbb{R}^{l-1} \rightarrow \mathbb{R}^{l-1}$  by

$$F(\varphi) = M(x) - h^2 f(\varphi),$$

where

$$M = \begin{bmatrix} 2 & -1 & 0 & \dots & 0 \\ -1 & 2 & -1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 2 \end{bmatrix}$$

and

$$f(\varphi) = [\varphi_1^{1+\lambda} + \varphi_1^2, \varphi_2^{1+\lambda} + \varphi_2, \dots, \varphi_{l-1}^{1+\lambda} + \varphi_{l-1}^2]^T.$$

Then, the Fréchet-derivative  $F'$  of operator  $F$  is given by

$$F'(\varphi) = M - (1 + \lambda)h^2 \begin{bmatrix} \varphi_1^\lambda & 0 & 0 & \dots & 0 \\ 0 & \varphi_2^\lambda & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & \varphi_{l-1}^\lambda \end{bmatrix} - 2h^2 \begin{bmatrix} \varphi_1 & 0 & 0 & \dots & 0 \\ 0 & \varphi_2 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & \varphi_{l-1} \end{bmatrix}. \quad (22)$$

We shall use a special case of method (2) given by

$$\begin{aligned} \psi_n^{(1)} &= \psi_n - F'(\psi_n)^{-1}F(\psi_n) \\ \psi_n^{(2)} &= \psi_n^{(1)} - F'(\psi_n)^{-1}F(\psi_n^{(1)}) \\ &\vdots \\ \psi_n^{(k)} &= \psi_n^{(k-1)} - F'(\psi_n)^{-1}F(\psi_n^{(k-1)}) \\ \psi_{n+1} &= \psi_n^{(k)}. \end{aligned} \quad (23)$$

Let  $\lambda = \frac{1}{2}$ ,  $k = 3$  and  $l = 10$ . In this way, we obtain a  $9 \times 9$  system. A good initial approximation is  $10 \sin \pi t$  since a solution to (20) vanishes at the end points and is positive at the interior. This approximation gives the vector

$$\xi = \begin{bmatrix} 3.0901699423 \\ 5.877852523 \\ 8.090169944 \\ 9.510565163 \\ 10 \\ 9.510565163 \\ 8.090169944 \\ 5.877852523 \\ 3.090169923 \end{bmatrix},$$

which by using (23) leads to

$$\psi_0 = \begin{bmatrix} 2.396257294 \\ 4.698040582 \\ 6.677432200 \\ 8.038726637 \\ 8.526409945 \\ 8.038726637 \\ 6.6774432200 \\ 4.698040582 \\ 2.396257294 \end{bmatrix}.$$

Using vector  $\psi_0$  as the initial vector in (23), we get the solution  $\psi^*$  given by

$$\psi^* = \psi_6 = \begin{bmatrix} 2.394640795 \\ 4.694882371 \\ 6.672977547 \\ 8.033409359 \\ 8.520791424 \\ 8.033409359 \\ 6.672977547 \\ 4.694882371 \\ 2.394640795 \end{bmatrix}.$$

Notice that the operator  $F'$  given in (22) is not Lipschitz.

### References

[1] I. K. ARGYROS, *On the solution of equations with non differentiable and Ptak error estimates*, BIT **30**(1990), 752–754.

[2] I. K. ARGYROS, *On a two point Newton like method of convergence order two*, International J. Comput. Math. **82**(2005), 210–213.

[3] I. K. ARGYROS, *A Kantorovich-type analysis for a fast iterative method for solving nonlinear equations*, J. Math. Anal. and Appl. **332**(2007), 97–108.

[4] I. K. ARGYROS, *Computational theory of iterative methods*, Series Studies in Computational Mathematics 15, Elsevier Publ. Co., New York, 2007.

[5] I. K. ARGYROS, A. A. MAGREÑÁN, *Iterative methods and their dynamics with applications*, CRC Press, New York, 2017.

[6] I. K. ARGYROS, S. GEORGE, N. THAPA, *Mathematical modeling for the solution of equations and systems of equations with applications*, Volume-I, Nova Publishes, New York, 2018.

[7] I. K. ARGYROS, S. GEORGE, N. THAPA, *Mathematical modeling for the solution of equations and systems of equations with applications*, Volume-II, Nova Publishes, New York, 2018.

[8] D. F. HAN, *The majorant method and convergence for solving non differentiable equations in Banach spcae*, Appl. Math. Comput. **118**(2001), 73–82.

[9] M. A. HERNÁNDEZ, M. J. RUBIO, *The secant method for non differentiable operators*, Appl. Math. Lett. **15**(2002), 395–399.

[10] M. A. HERNÁNDEZ AND M. J. RUBIO, *Semilocal convergence of the secant method under mild convergence conditions of differentiability*, Comput. Math. Appl. **44**(2002), 277–285.

[11] A. A. MAGREÑÁN, I. K. ARGYROS, *Iterative algorithms I*, Nova Publishes, New York, 2017.

[12] A. A. MAGREÑÁN, I. K. ARGYROS, *Iterative algorithms II*, Nova Publishes, New York, 2017.

[13] J. M. ORTEGA, R. C. RHEINBOLDT, *Iterative solution of nonlinear equations in several variables*, Academic Press, New York, 1970.

[14] H. M. REN, *New sufficient convergence conditions of the secant method for non differentiable operators*, Appl. Math. Comput. **182**(2006), 1255–1259.

[15] J. W. SCHMIDT, *Regula-falsi Verfahren mit konsistenter Steigung and Majorantenpinzip*, Period. Math. Hungar. **5**(1974), 187–193.

- [16] A. SERGEEV, *On the method of choice*, Sibirsk. Math. Z. **2**(1961), 282–289.
- [17] P. P. ZABREJKO, D. F. NGUEN, *The majorant method in the theory of Newton Kantorovich approximations and the Pták error estimates*, Numer. Func. Anal. Optimiz. **9**(1987), 671–684.